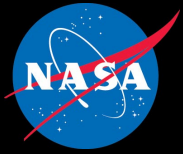


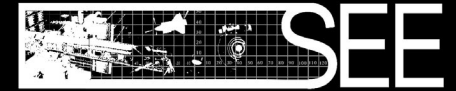
The Synergistic Engineering Environment

<http://centauri.larc.nasa.gov/see>

June 2005



SEE: What is it?



The Synergistic Engineering Environment is a software tool for space mission visualization and analysis.

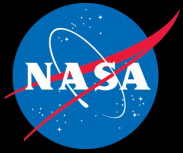
Another 3D Visualization Toolkit?

The SEE has followed several development priorities that distinguish it from existing tools:

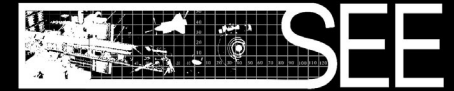
Enable users to effectively **investigate mission events that span very great or very small scales of space and time.**

Allow performance models and object geometry of **mixed-fidelity** to appear in the same virtual environment.

Maintain **extensible and multi-platform compatible** source code so that the unique requirements of a small group of users can be met without major software architecture changes.



SEE History and Background



Description / Goals

Simulate and visualize space mission scenarios by integrating spacecraft performance models and realistic object geometry in a 3D virtual environment.

Facilitate the understanding of a problem trade space.

Perform spacecraft configuration and system trade studies.

Provide an open, customizable code architecture that can accommodate new models as the system studies advance.

Brief History

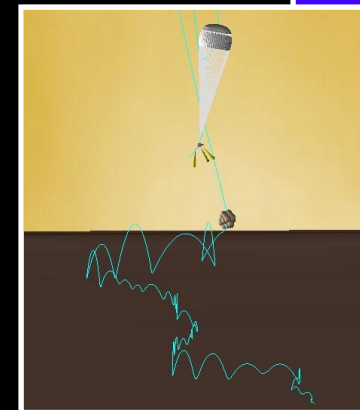
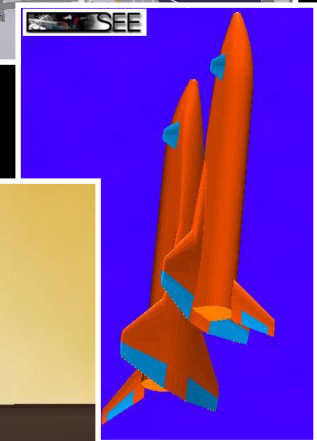
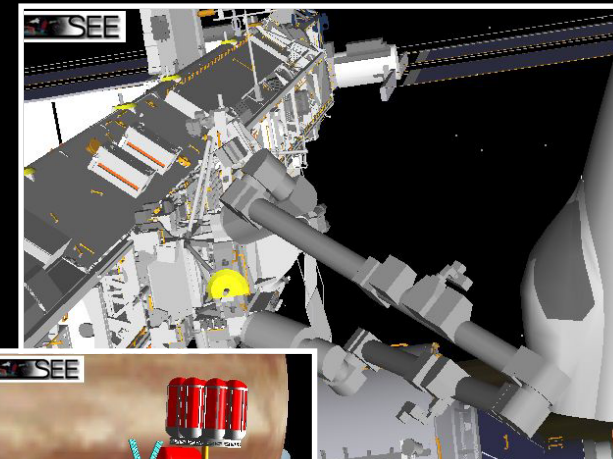
Research initially funded by NASA Chief Engineer and Code M Advanced Programs

Adopted by Intelligent Synthesis Environment Program as the International Space Station Large Scale Environment

In use by the ISS VIPER team and Mission Operations at JSC

Scope of SEE broadened under Revolutionary Aerospace Systems Concepts and Engineering for Complex Systems

In use by Vehicle Analysis Branch in support of Mars Scout and Next Generation Launch Vehicles



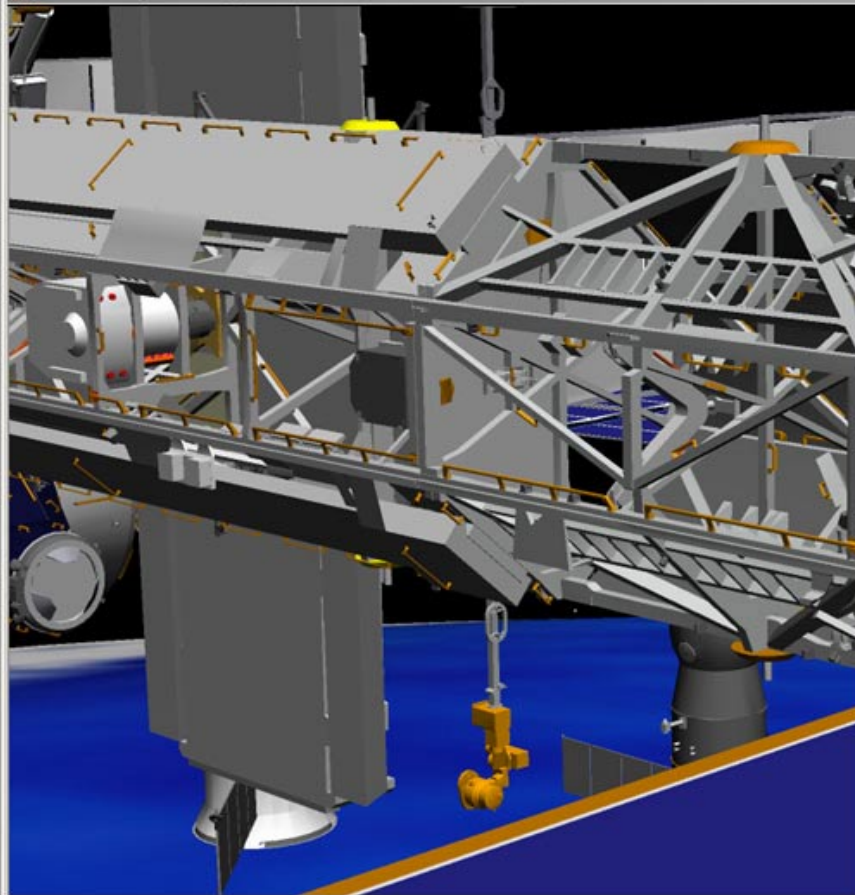
SEE - Rev Q s044 10a_2 (modified)

File Mission Analysis View Tools Bookmarks Macros Media Window Help

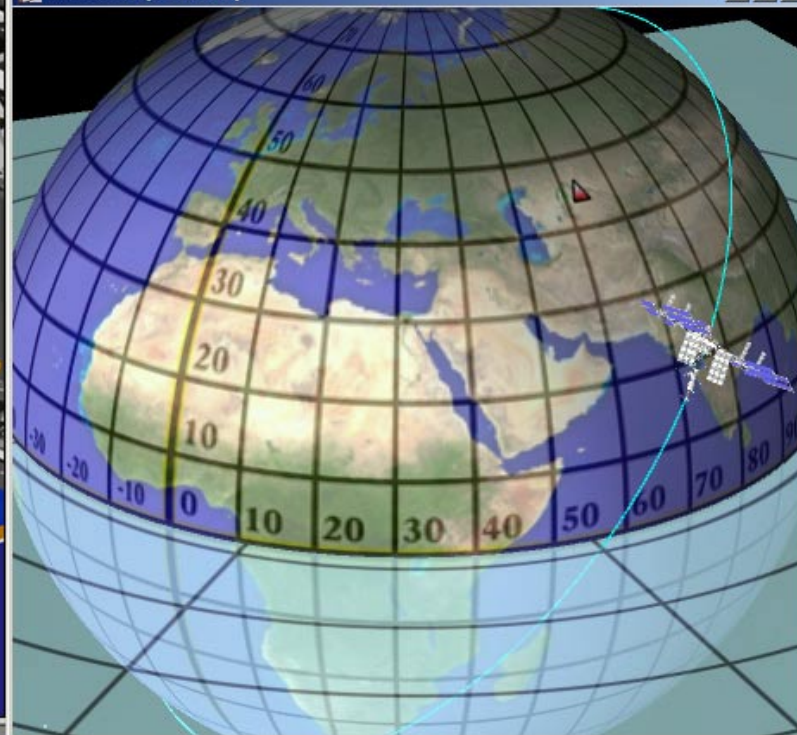


SYNERGISTIC ENGINEERING ENVIRONMENT

Camera 5 (949x528)



Camera 4 (461x431)



Camera Navigation

Warp Factor

1

Tether

Earth

Field of View

H: 13.77° V: 12.87°

☐ Synchronous View

☐ Fixed Gaze Object

Off

Date and Time

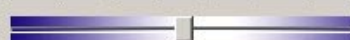
UTC 2008 01 01

13 : 34 : 40.000



1.0

min/sec



RT

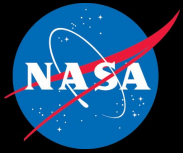
1

2

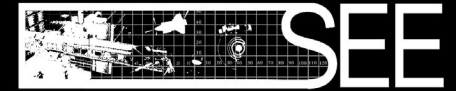
3

set

STATUS: New camera created.



General Capabilities



True to scale solar system

Effective navigation control across large time and space dimensions (milliseconds to years; centimeters to AUs)

Scaling control within the environment

Maintains analysis integrity (no adverse impact)

Critical to visualization

Automated processes for import of spacecraft models into the environment

High resolution CAD models with articulated rigid bodies through custom IDEAS/ProE model export capabilities

Fast path to analysis (CAD → STL → SEE)

Artists' conceptual models

Analysis capabilities

Collision detection/proximity measurement

Power Subsystem analysis

Line of sight viewing

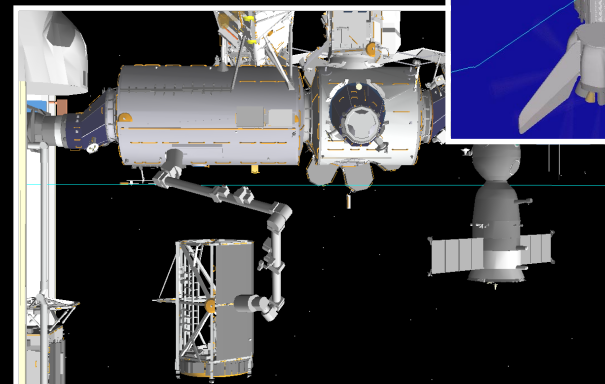
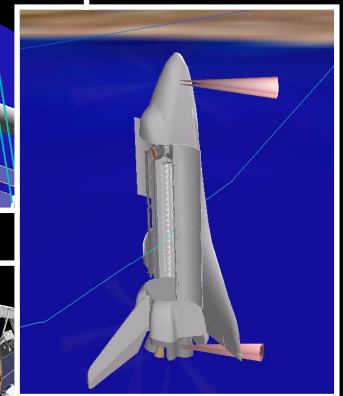
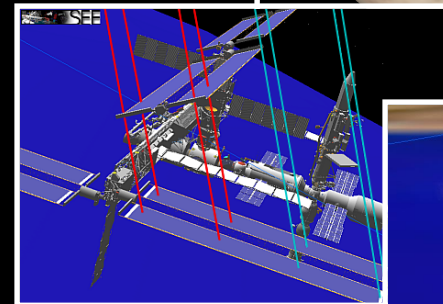
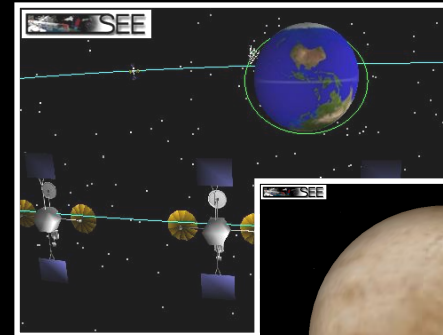
Thruster firing visualization →

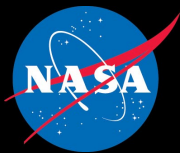


Supplemental data visualization

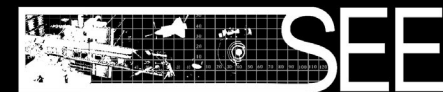
Inverse and forward kinematics for robotic operations

Manipulate geometry models





Trajectory Visualization



Crafts can be placed in the SEE using:

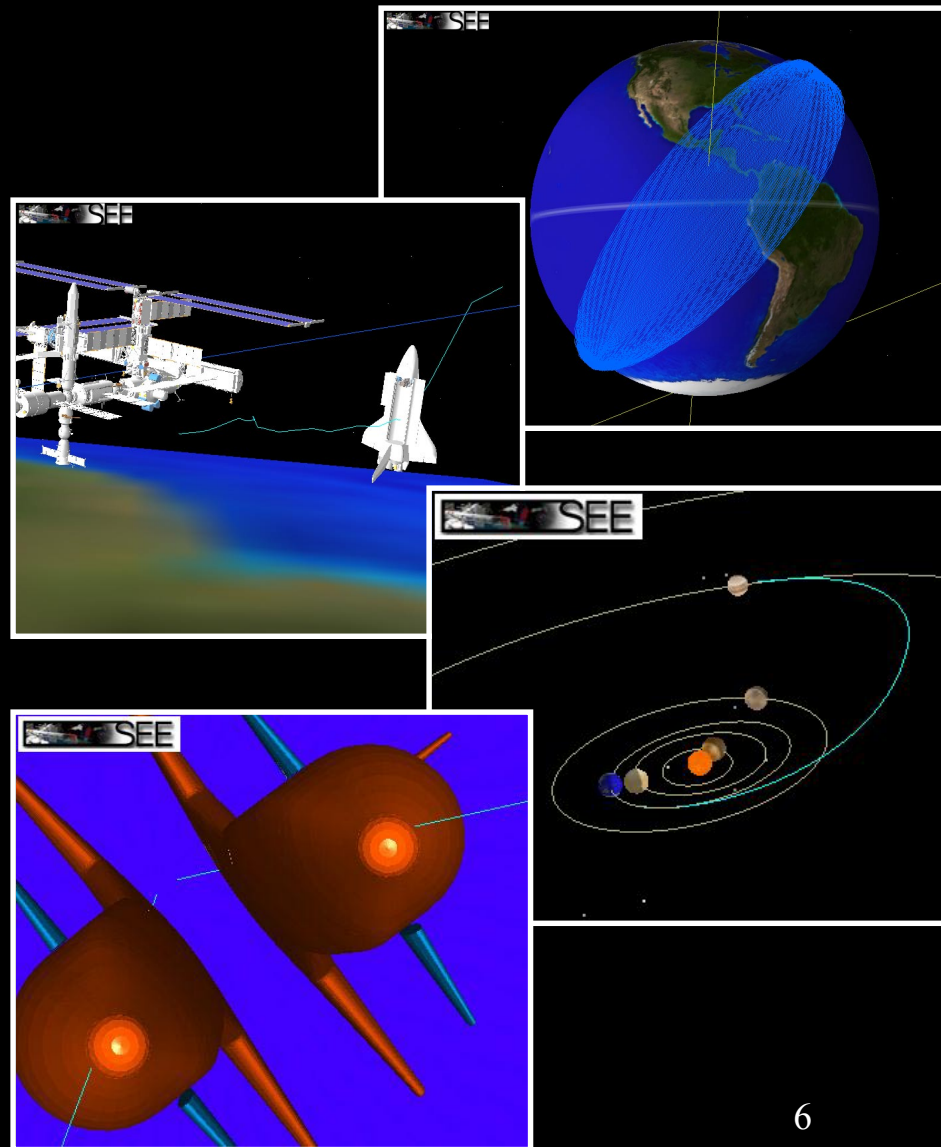
- Classical six orbital elements
- Two Line Element Set using SxP4
- Imported analysis data
- Archived telemetry data
- Integrated ARCD software

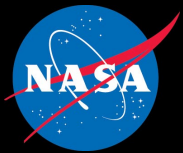
Trajectories can be imported:

- Relative to any primary
- Relative to any point
- Relative to another craft (prox ops)

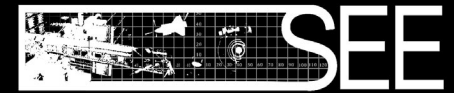
Rigid bodies can be articulated using:

- Imported analysis data
- Auto-suntracking feature
- Scripted motion interface





Enhanced Interface Capabilities



Navigation and Time controls

Attach your camera to any reference frame

Bookmarks save time and position

VCR-style time controls

Icons

Reference frame visualization

Velocity direction vectors

Object direction vectors

Plotting

Time bar shows the simulation's current location within the plot

All plot data is saved to file for any external plotting needs

Plot the Euler sequence between two reference frames

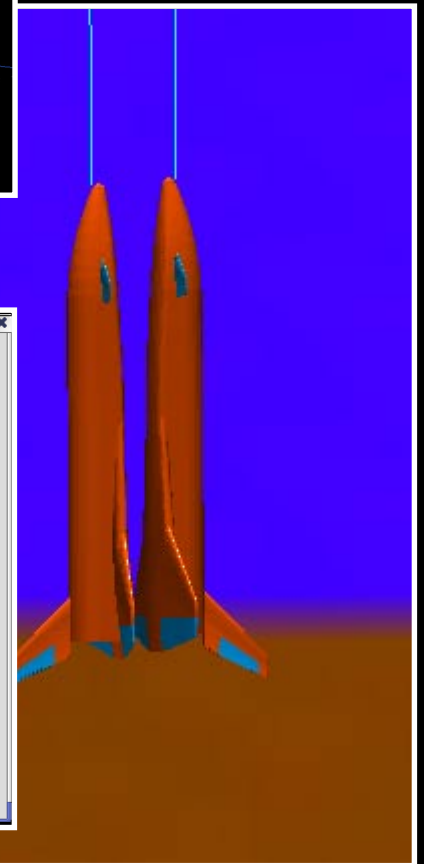
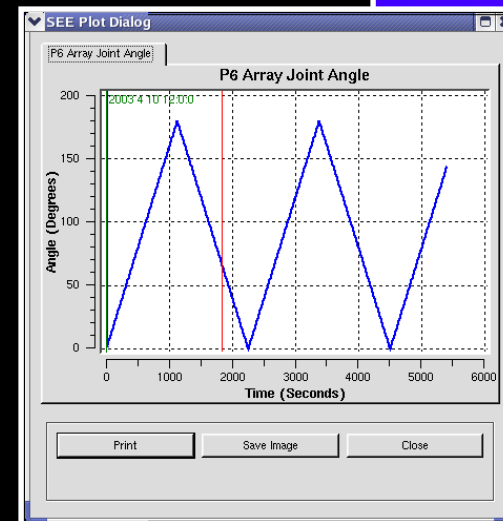
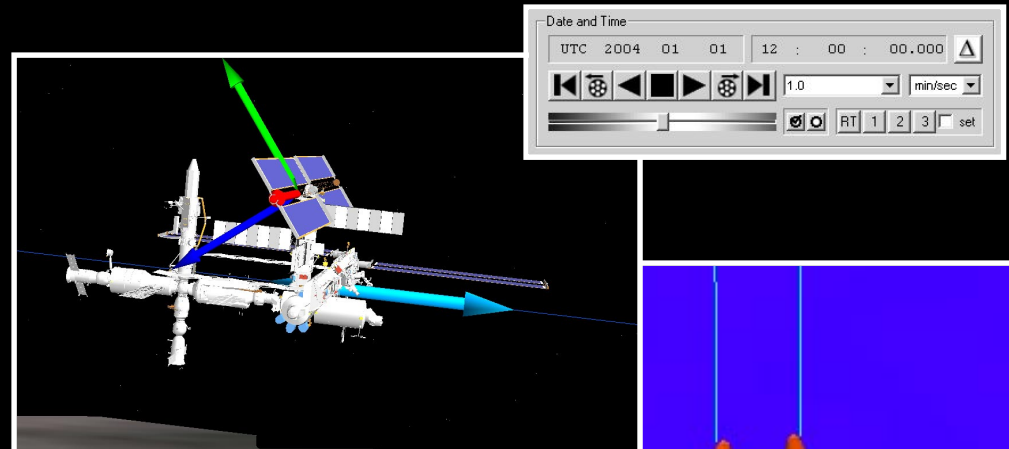
Plot the angle between vectors

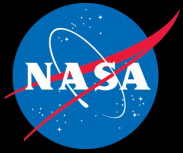
Plot a jet firing history

Media

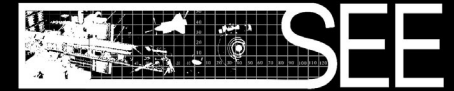
Still image capture (jpeg, gif, bmp, etc.)

Time based motion capture (avi)





Extensible Architecture Design

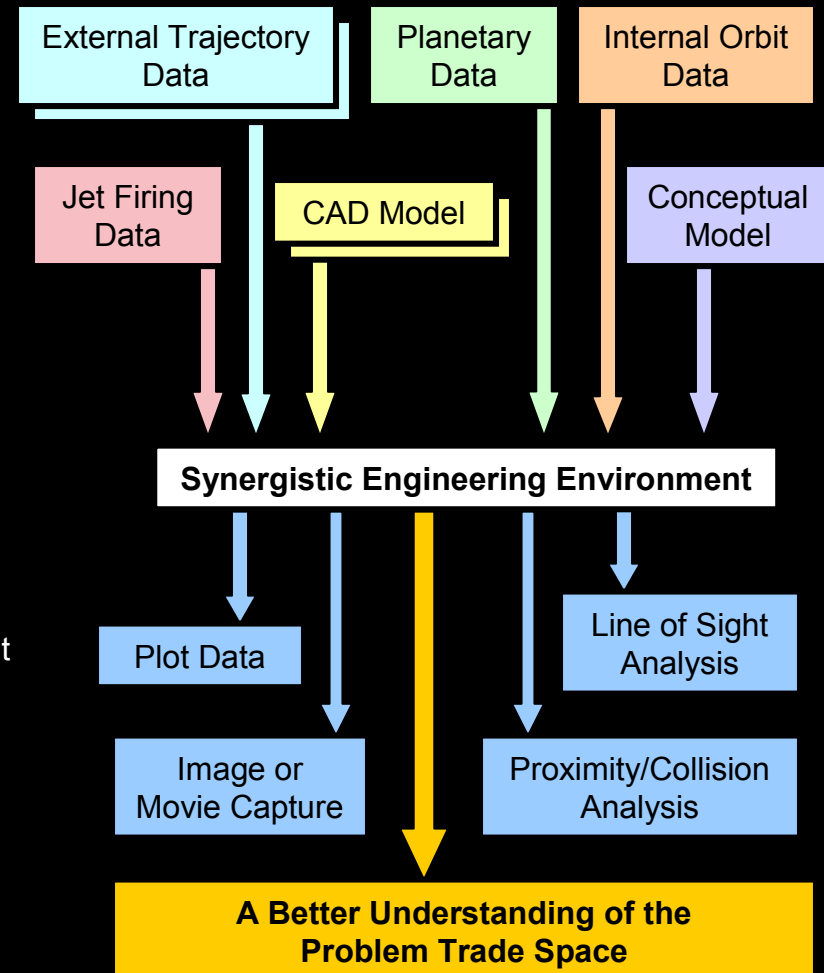


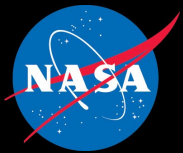
Flexible and Robust

- Object Oriented software design
- Cross platform **Windows, Linux, and Irix**
- Scalable from laptops to high end workstations

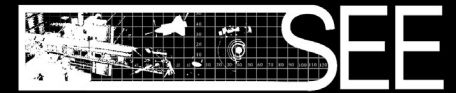
End-User Customization

- Any number of crafts or other objects
- Each object can have its own unique dynamics model
- Imported data can be viewed relative to an inertial point or within the integrated solar system
- Customizable solar system
 - Any number of planets and moons
 - Internal dynamics model or imported data
- Design analyses with internal macro language





Applications



International Space Station

Multiple Installations within the VIPER Team
Multiple Installations within Mission Operations
and Lockheed

Architectures, Missions, and Science Branch

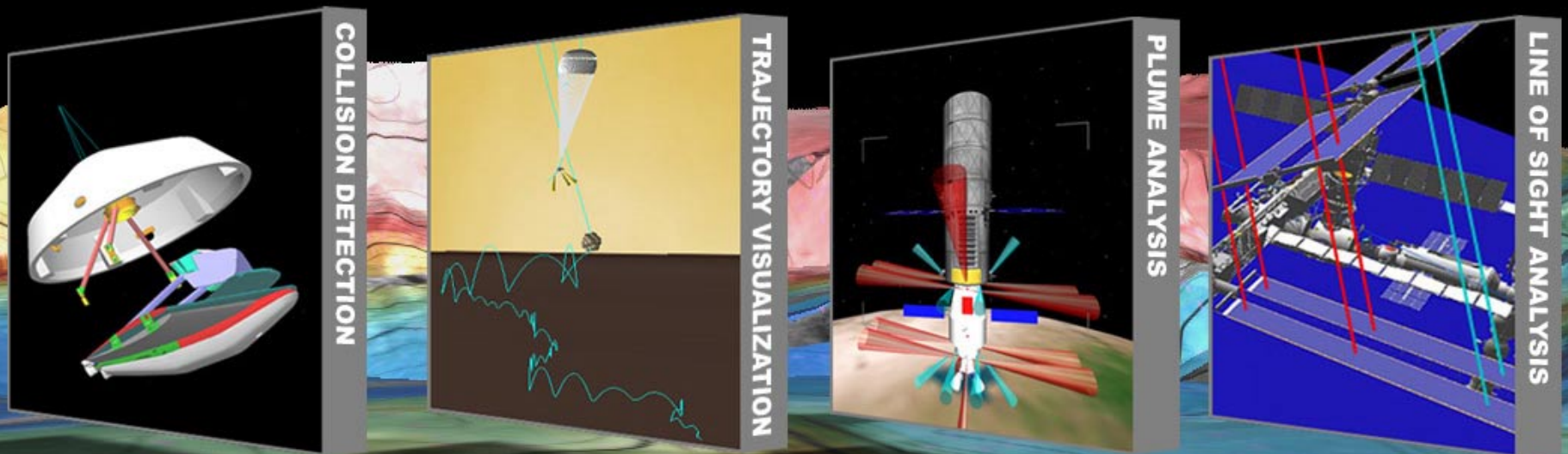
Support ISS reconfiguration analysis
Visualization and Analysis of several RASC studies
Visualization of Lunar Mission Studies

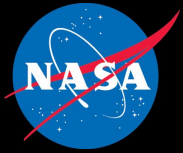
Vehicle Analysis Branch

Mars Scout ARES Separation Analysis
Hyper-X pre and post flight analysis
NGLT analysis
MER landing and descent recreation

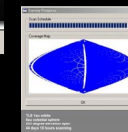
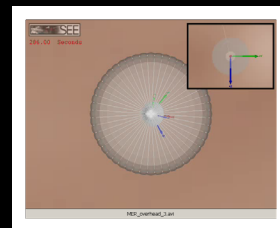
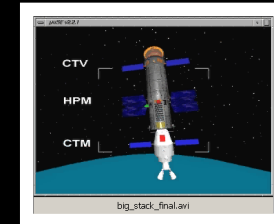
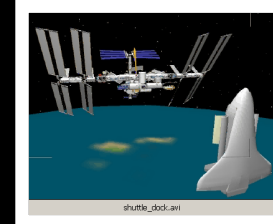
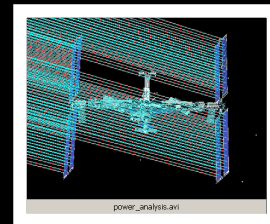
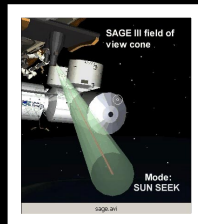
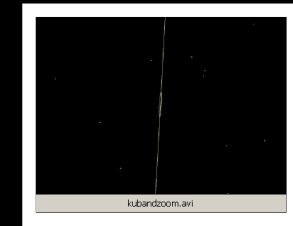
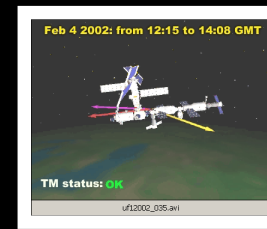
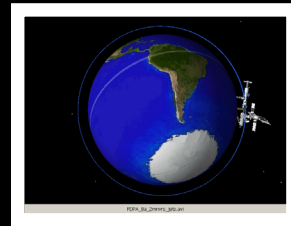
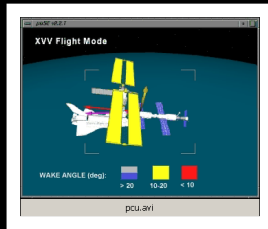
NASA Headquarters

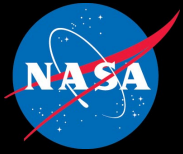
Installation within the Space Operations Room
ISS Situational Awareness



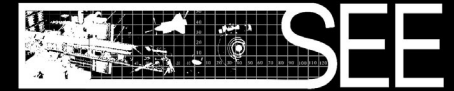


Applications





Distinguishing Features



The Unique Capabilities of the SEE Include:

Extensible object oriented code architecture and developer documentation to support new application requirements and integration of existing analysis tools

Automated process for importing object geometry from CAD systems such as IDEAS

Interactive craft assembly manipulation capabilities (e.g. move parts of the craft around to examine instrument placement options)

Macro language for automation of analysis that requires large numbers of repeated trials

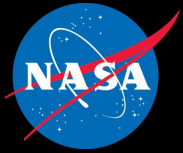
High performance rendering to support detailed geometry or large numbers of entities in the scene (e.g. 50,000 asteroids)

Unlimited object scaling (e.g. scaling planets and crafts allows surface features and craft orientation details in the same view)

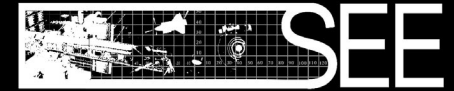
Novel time-rate controls allow browsing jet firing histories and interplanetary trajectories in the same sim.

Support for unique input file formats and customized planetary body data to allow the analyst to control all objects in the scene using data produced by external tools.

Wide platform compatibility (Windows, Linux, Irix, soon Mac)



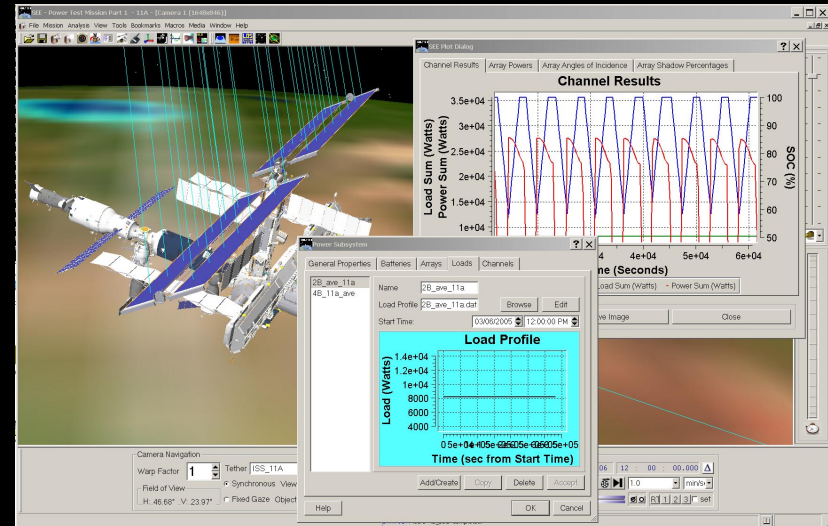
Future Directions



Further development and support from ISS Program for subsystem level analysis

Improved situational awareness

- Real-time telemetry feed
- Enhancements to data visualization
- Ground track
- External camera views
- Real time shadowing

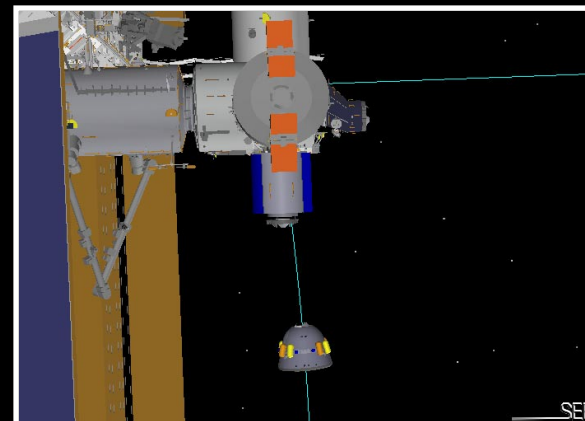


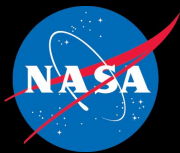
Proximity operations analysis

- Integrated 6-DOF docking analysis software
- Visualization of thruster firing data

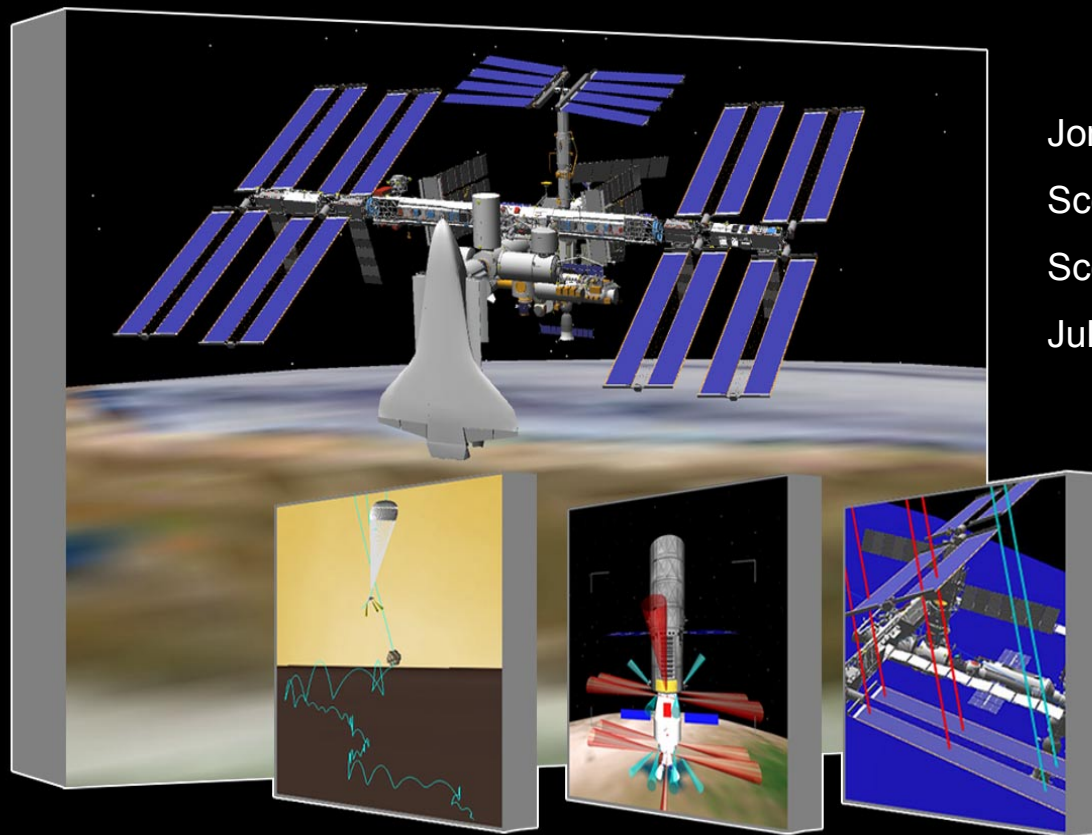
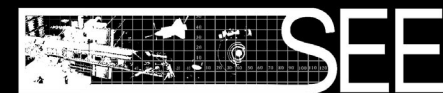
Distributed simulation capabilities

- Real-time collaboration between SEE users





SEE Team



Jonathan Cruz Technical Monitor

Scott Angster Lead

Scott Chaney

Darrell Caldwell

Julia Glaeser

Matt Toniolo